

Pólhnit:

$$\mathbf{v} = \dot{\mathbf{r}} = \dot{r}\mathbf{e}_r + r\dot{\theta}\mathbf{e}_\theta$$

$$\mathbf{a} = \dot{\mathbf{v}} = (\ddot{r} - r\dot{\theta}^2)\mathbf{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\mathbf{e}_\theta$$

Sívalningshnit:

$$x = r \cos \phi, \quad y = r \sin \phi, \quad z = z$$

$$\mathbf{v} = \dot{\mathbf{r}} = \dot{r}\mathbf{e}_r + r\dot{\phi}\mathbf{e}_\phi + \dot{z}\mathbf{e}_z$$

Kúluhnit:

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

$$dv = r^2 \sin \theta dr d\theta d\phi$$

$$\mathbf{v} = \dot{r}\mathbf{e}_r + r\dot{\theta}\mathbf{e}_\theta + r \sin \theta \dot{\phi}\mathbf{e}_\phi$$

Vigrar:

$$\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = (\mathbf{A} \cdot \mathbf{C})\mathbf{B} - (\mathbf{A} \cdot \mathbf{B})\mathbf{C}$$

Kraftlögjmál:

$$\mathbf{p} = m\mathbf{v}, \quad \mathbf{F} = \frac{d\mathbf{p}}{dt}, \quad \Delta\mathbf{p} = \int \mathbf{F} dt$$

$$T = \frac{1}{2}mv^2, \quad \mathbf{F} \cdot \mathbf{v} = \frac{dT}{dt}$$

$$\mathbf{v} = \boldsymbol{\omega} \times \mathbf{r}, \quad \mathbf{L} = \mathbf{r} \times \mathbf{p}, \quad \dot{\mathbf{L}} = \mathbf{r} \times \mathbf{F}$$

Geymið kraftsvið:

$$\mathbf{F} = -\nabla U, \quad \oint \mathbf{F} \cdot d\mathbf{r} = 0$$

$$E = T + U = \text{fasti}$$

Sveiflur:

$$F(x) = m\ddot{x} = -kx,$$

$$\omega_0 = \sqrt{k/m}, \quad \tau_0 = \frac{2\pi}{\omega_0}$$

$$x = a \cos(\omega_0 t - \phi)$$

eða

$$x = B \cos(\omega_0 t) + C \sin(\omega_0 t)$$

Deyfing:

$$\beta = b/(2m)$$

$$\ddot{x} + 2\beta\dot{x} + \omega_0^2 x = 0$$

með lausn:

$$x = Ae^{-\beta t} \cos(\omega_1 t - \delta)$$

ef $\omega_1^2 = \omega_0^2 - \beta^2 > 0$ (vandeyfing)

Pvinguð sveifla:

$$x = \frac{(F_0/m)}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\omega^2\beta^2}} \cos(\omega t - \delta)$$

Fourier-röð:

$$F(t) = a_0/2 + \sum_{n=1}^{\infty} (a_n \cos(n\omega t) + b_n \sin(n\omega t))$$

með (τ er lotan):

$$a_n = \frac{2}{\tau} \int_0^\tau F(t) \cos(n\omega t) dt$$

$$b_n = \frac{2}{\tau} \int_0^\tau F(t) \sin(n\omega t) dt$$

Pendúll:

$$\ddot{\theta} + \omega_0^2 \sin \theta = 0, \quad \omega_0^2 = g/l$$

Pyngdarsvið:

$$\mathbf{F} = -\frac{Gm_1m_2}{r^2}\mathbf{e}_r, \quad \mathbf{g} = \frac{\mathbf{F}}{m} = -\nabla\Phi$$

þar sem:

$$\Phi = -\frac{Gm_2}{r}, \quad \Phi = -G \int \frac{\rho}{r} dv, \quad U = m\Phi$$

Lögmál Gauß:

$$\int_S \mathbf{g} \cdot \mathbf{n} da = -4\pi G \int_V \rho dv, \quad \nabla \cdot \mathbf{g} = -4\pi G\rho$$

Jafna Poissons:

$$\nabla^2 \Phi = 4\pi G\rho$$

Jafna Eulers:

$$\frac{\partial f}{\partial y} - \frac{d}{dx} \left(\frac{\partial f}{\partial y} \right) = 0$$

Fall Lagrange:

$$L(q_j, \dot{q}_j, t) = T - U, \quad \delta \int_1^2 L dt = 0$$

$$\frac{\partial L}{\partial q_j} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \right) = 0$$

$$p_j = \frac{\partial L}{\partial \dot{q}_j}$$

Fall Hamiltons:

$$H = \sum_j \dot{q}_j \frac{\partial L}{\partial \dot{q}_j} - L$$

$$H = H(q_i, p_i, t)$$

Jöfnur Hamiltons:

$$\frac{\partial H}{\partial p_k} = \dot{q}_k, \quad \frac{\partial H}{\partial q_k} = -\dot{p}_k$$

Geymið kerfi:

$$\frac{\partial H}{\partial t} = 0, \quad H = T + U$$

Miðlægir kraftar:

$$\mathbf{F} = -\frac{\partial U(r)}{\partial r} \mathbf{e}_r, \quad \mu \equiv \frac{m_1 m_2}{m_1 + m_2}$$

$$L = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\theta}^2) - U(r)$$

$$\left(\frac{d^2 u}{d\theta^2} \right) + u = -\frac{\mu}{\ell^2} \frac{F(1/u)}{u^2}$$

$$u = 1/r, \quad \ell = \mu r^2 \dot{\theta}$$

$$\theta(r) = \int \frac{(l/r^2) dr}{\sqrt{2\mu(E + \frac{k}{r} - \frac{l^2}{2\mu r^2})}} + \text{fasti}$$

Reikistjörnur/gervitungl:

$$F(r) = -\frac{k}{r^2}, \quad r = \frac{\alpha}{1 + \epsilon \cos \theta}$$

Stöðug hringbraut ef:

$$\frac{F'(\rho)}{F(\rho)} > -\frac{3}{\rho}$$

Safn agna:

$$M\mathbf{R} = \sum_{\alpha} m_{\alpha} \mathbf{r}_{\alpha}, \quad M\mathbf{R} = \int \mathbf{r} \rho dv$$

$$\mathbf{F} = M\ddot{\mathbf{R}}, \quad \mathbf{N} = \sum_{\alpha} \mathbf{r}_{\alpha} \times \mathbf{F}_{\alpha}$$

$$\mathbf{L} = \sum_{\alpha} \mathbf{r}_{\alpha} \times m_{\alpha} \mathbf{v}_{\alpha}, \quad \mathbf{N} = \dot{\mathbf{L}}$$

$$T = \frac{1}{2} M \dot{\mathbf{R}}^2 + \frac{1}{2} I_{cm} \omega^2$$

Árekstrar:

$$\sum \mathbf{p} = \text{fasti}, \quad T_{\text{eftir}} = T_{\text{fyrir}} + Q$$

$$\epsilon = \frac{|v_2 - v_1|}{|u_2 - u_1|}, \quad \tan \psi = \frac{\sin \theta}{\cos \theta + (m_1/m_2)}$$

Viðmiðunarkerfi:

$$\mathbf{r}' = \mathbf{R} + \mathbf{r}$$

$$\left(\frac{d\mathbf{Q}}{dt} \right)_{K'} = \left(\frac{d\mathbf{Q}}{dt} \right)_K + \boldsymbol{\omega} \times \mathbf{Q}$$

$$\mathbf{a}_{\text{eff}} = \mathbf{a} - \ddot{\mathbf{R}} - \boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r}) - 2\boldsymbol{\omega} \times \mathbf{v}_r - \dot{\boldsymbol{\omega}} \times \mathbf{r}$$

Stjarfhlutir:

$$I_{ij} = \sum_{\alpha} m_{\alpha} (r_{\alpha}^2 - x_{j\alpha}^2), \quad \text{ef i=j}$$

$$I_{ij} = - \sum_{\alpha} m_{\alpha} x_{i\alpha} x_{j\alpha}, \quad \text{ef i} \neq \text{j}$$

$$I_{ij} = \int_V \rho(\mathbf{r}) \left(\delta_{ij} \sum_k x_k^2 - x_i x_j \right) dv$$

$$\mathbf{L} = \{\mathbf{I}\} \cdot \boldsymbol{\omega}$$

$$T_{\text{rot}} = \frac{1}{2} \boldsymbol{\omega} \cdot \{\mathbf{I}\} \cdot \boldsymbol{\omega} = \frac{1}{2} \boldsymbol{\omega} \cdot \mathbf{L} = \frac{1}{2} \sum_{i,j} I_{ij} \omega_i \omega_j$$

Regla Steiners:

$$I_{jj,cm} = I_{jj} - Ma^2$$

Meginásar - höfuðásar:

$$|\mathbf{I} - I\mathbf{1}| = 0, \quad \mathbf{I}' = \boldsymbol{\lambda} \mathbf{I} \boldsymbol{\lambda}^t, \quad \mathbf{I}' = \boldsymbol{\lambda} \mathbf{I} \boldsymbol{\lambda}^{-1}$$

Horn Eulers:

ϕ um z' , θ um x'' , ψ um z

$$\omega = (\dot{\phi} \sin \theta \sin \psi + \dot{\theta} \cos \psi, \dot{\phi} \sin \theta \cos \psi - \dot{\theta} \sin \psi, \dot{\phi} \cos \theta + \dot{\psi})$$

Jöfnur Eulers:

$$I_1\dot{\omega}_1 - (I_2 - I_3)\omega_2\omega_3 = N_1$$

$$I_2\dot{\omega}_2 - (I_3 - I_1)\omega_3\omega_1 = N_2$$

$$I_3\dot{\omega}_3 - (I_1 - I_2)\omega_1\omega_2 = N_3$$

$$I_1 = I_2 \text{ ef } x_3 \text{ er samhverfuás og}$$

$$\mathbf{N} = \mathbf{0} \text{ gefur } \Omega = (I_3 - I_{12})\omega_3/I_{12}$$

Snúður:

$p_\psi = I_3\omega_3 = \text{fasti}$, $p_\phi = \text{fasti}$

$$E = \frac{1}{2}I_{12}(\dot{\phi} \sin^2 \theta + \dot{\theta}^2) + \frac{1}{2}I_3\omega_3^2 + Mgh \cos \theta = \text{fasti}$$

Pólvelta:

$$\dot{\phi}_{0(-)} \approx Mgh/I_3\omega_3$$

$$\dot{\phi}_{0(+)} \approx I_3\omega_3/(I_1 \cos \theta_0)$$

Tengdar sveiflur um jafnvægisstöðu:

$$T = \frac{1}{2} \sum_{j,k} m_{jk} \dot{q}_j \dot{q}_k$$

$$U = \frac{1}{2} \sum_{j,k} A_{jk} q_j q_k$$

$$\text{öll } q \text{ cos-föll af } \omega t \text{ ef } |A_{jk} - \omega^2 m_{jk}| = 0,$$

$$n \text{ rætur, hlutföll hnitanna } a_1 : a_2 : a_3$$

$$\text{finnast út úr } \sum_j (A_{jk} - \omega^2 m_{jk}) a_j = 0$$

$$q_j(t) = \sum_r a_{jr} \cos(\omega_r t - \delta_r)$$

skv. upphafsskilyrðum.

$$\{\mathbf{A} - \omega^2 \mathbf{M}\} \mathbf{a} = 0$$

$$\mathbf{U}^t \mathbf{A} \mathbf{U} = \mathbf{A}_{\text{diag}}, \quad \mathbf{U}^t \mathbf{M} \mathbf{U} = \mathbf{1}$$

Örfáar jöfnur úr stærðfræði

$$\cos 2\theta = \cos^2 \theta - \sin^2 \theta$$

$$\sin 2\theta = 2 \cos \theta \sin \theta$$

$$\int \sin^2 x \, dx = \frac{x}{2} - \frac{1}{4} \sin 2x$$

$$\int \cos^2 x \, dx = \frac{x}{2} + \frac{1}{4} \sin 2x$$

$$\int dx \ln(a + bx) = \left(x + \frac{a}{b} \right) \ln(a + bx) - x$$

$$\sin(A \pm B) = \sin A \cos B \pm \cos A \sin B$$

$$\cos(A \pm B) = \cos A \cos B \mp \sin A \sin B$$

$$(1 \pm x)^{\frac{1}{2}} = 1 \pm \frac{1}{2}x - \frac{1}{8}x^2 \pm \frac{1}{16}x^3 + \dots$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} + \dots$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} + \dots$$

$$\ln(1 + x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots$$