

Dæmi 1

Massi m í
 $(+2,0,0)$ og $(-2,0,0)$,
 $(0,+2,0)$ og $(0,-2,0)$

① $I_{ij} = \sum_k M_k \left(S_{ij} \sum_k x_{x,k}^2 - x_{x,i} x_{x,j} \right)$

$$= ma^2 \begin{pmatrix} 8 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 10 \end{pmatrix}$$

② Festum

$\bar{\omega} = \frac{\omega}{\sqrt{3}} (1,1,1)$

$\rightarrow \bar{I} = \bar{I} \cdot \bar{\omega} = ma^2 \begin{pmatrix} 8 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 10 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \frac{\omega}{\sqrt{3}}$
 $= \frac{ma^2 \omega}{\sqrt{3}} (8, 2, 10)$

Dæmi 2

Athugum samhverfan snúð án ytra kraftvægis eins og fjallað er um í undirkafa 13.20.1 í bók DC. Umfjöllunin endar með jöfnu (13.139) fyrir tímamaflieðu

Eulerhornsins ϕ , en þeim lausn sem fall af tímanum t er sjaldan sett fram fyrir hornin því. Gerum ráð fyrir að snúðurinn sé á hreyfingu með jafnri veltu sem lýst er með jöfnu (13.119). Finníð tímapróun allra hornanna.

Snúður án ytra vægis →

$$\left\{ \begin{array}{l} (I_1 - I_3)\omega_2 \omega_3 - I_1 \dot{\omega}_1 = 0, \quad I_1 = I_2 \\ (I_3 - I_1)\omega_3 \omega_1 - I_1 \dot{\omega}_2 = 0 \\ I_3 \dot{\omega}_3 = 0 \quad \rightarrow \underline{\omega_3 = \text{fast}} \\ \dot{\omega}_1 + \Omega \omega_2 = 0 \\ \dot{\omega}_2 - \Omega \omega_1 = 0 \end{array} \right.$$

$\Omega = \left(\dot{\psi} \right) = \left(\frac{I_3 - I_1}{I_1} \right) \omega_3$
 \uparrow_{fast}

(*)

③

② Setjum $\hat{n} = \frac{1}{\sqrt{3}} (1,1,1)$

$\bar{I} \cdot \hat{n} = ma^2 \frac{\omega}{3} 2\sigma = |\bar{I}| \cos \gamma$

$|\bar{I}| = \omega ma^2 \frac{1}{\sqrt{3}} \sqrt{64 + 4 + 100} \approx ma^2 \omega 7,4833$

$\rightarrow \cos \gamma = \frac{\bar{I} \cdot \hat{n}}{|\bar{I}|} \approx 0,89087 \rightarrow \gamma = 0,4715 \text{ rad} \approx 27^\circ$

þar sem γ er hornið milli vigranna. Mikilvægt er að munna að hér er allt reiknað í hnítakerfi hlutar. Sú aðferðafræzi einfaldar alla reikningana, það eru ein mikilvægustu skilboðin úr köflunum um snúningshreyfingu og hnítakerfi sem ekki eru tregðukerfi.

④

Höfum (13.86-88)

$$\left\{ \begin{array}{l} \omega_1 = \dot{\phi} \sin \theta \sin \psi + \dot{\theta} \cos \psi \\ \omega_2 = \dot{\phi} \sin \theta \cos \psi - \dot{\theta} \sin \psi \\ \omega_3 = \dot{\phi} \cos \theta + \dot{\psi} \end{array} \right. \quad (z)$$

notum með (*) →

$\dot{\phi} \sin \theta \sin \psi + \dot{\theta} \cos \psi = A \cos(\Omega t + \gamma) \quad (a)$

$\dot{\phi} \sin \theta \cos \psi - \dot{\theta} \sin \psi = A \sin(\Omega t + \gamma) \quad (b)$

$\dot{\phi} \cos \theta + \dot{\psi} = \text{fast} \equiv B$

til að uppfylla upphafsgildi

Nánum (a) · cosψ og (b) · sinψ →

$$\dot{\phi} \sin \theta \sin \psi \cos \psi + \dot{\theta} \cos^2 \psi = A \cos(\Omega t + \gamma) \cos \psi \quad (1)$$

$$\dot{\phi} \sin \theta \cos \psi \sin \psi - \dot{\theta} \sin^2 \psi = A \sin(\Omega t + \gamma) \sin \psi \quad (2)$$

① - ② :

$$\begin{aligned} \dot{\theta} &= A \cos(\Omega t + \gamma) \cos \psi - A \sin(\Omega t + \gamma) \sin \psi \\ &= A \cos(\Omega t + \gamma + \psi) \end{aligned}$$

jöfn velta → $\dot{\theta} = 0 \rightarrow A \cos(\Omega t + \gamma + \psi) = 0$
 $\rightarrow \Omega t + \gamma + \psi = \left(\frac{2n+1}{2}\right)\pi, \quad n = 0, 1, 2, 3, \dots$

(5)

$$\rightarrow \boxed{\psi = \psi_0 - \Omega t}, \quad \psi_0 = -\gamma + \frac{(2n+1)\pi}{2} \text{ upphafsgildi}$$

(a) · sinψ + (b) cosψ →

$$\dot{\phi} \sin \theta \sin \psi \sin \psi = A \cos(\Omega t + \gamma) \sin \psi$$

$$+ \dot{\phi} \sin \theta \cos \psi \cos \psi = A \sin(\Omega t + \gamma) \cos \psi$$

$$\rightarrow \dot{\phi} \sin \theta = A \sin(\Omega t + \gamma + \psi)$$

$$\rightarrow \dot{\phi} = \frac{A}{\sin \theta} \sin(\Omega t + \gamma + \psi) \quad (***)$$

notum í (2) og $\psi = \psi_0 - \Omega t \rightarrow \dot{\psi} = -\Omega$

$$\rightarrow \omega_3 = A \frac{\cos \theta}{\sin \theta} \sin(\Omega t + \gamma + \psi) - \Omega$$

$$= A \frac{\cos \theta}{\sin \theta} \sin(\Omega t + \gamma + \psi_0 - \Omega t) - \Omega$$

$$\rightarrow \omega_3 + \Omega = \frac{A}{\tan \theta} \sin(\gamma + \psi_0) = \frac{A}{\tan \theta} \sin\left(\frac{(2n+1)\pi}{2}\right)$$

$$= \frac{A}{\tan \theta}$$

$$\rightarrow \boxed{A = (\omega_3 + \Omega) \tan \theta}$$

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$$A = \left[\omega_3 + \left(\frac{I_3 - I_1}{I_1} \right) \omega_3 \right] + \tan \theta = \frac{I_3}{I_1} + \tan \theta$$

$$(***) \rightarrow \dot{\phi} = \frac{I_3 + \tan \theta}{I_1 \sin \theta} \sin(\Omega t + \gamma + \psi)$$

$$= \frac{I_3}{I_1} \frac{1}{\cos \theta} \sin(\gamma + \psi_0) \underbrace{\frac{(2n+1)\pi}{2}}_{\frac{2n+1}{2}\pi}$$

$$= \frac{I_3}{I_1} \frac{1}{\cos \theta}$$

$$\rightarrow \boxed{\phi = \phi_0 + \frac{I_3 t}{I_1 \cos \theta}}$$

virðist leng leis fyrir svör með einfalt útlit

(6)

(8)

Dæmi 3veltuhraði $\bar{\omega} = \Omega \hat{z}$ 

$$I_3 = \frac{MR^2}{2}, \quad I_1 = I_2 = I = \frac{MR^2}{4} + Ml^2$$

(9)

Steiner

$$\omega_3 = \Omega \cos \theta$$

$$\bar{\Gamma} = \bar{I} \cdot \bar{\omega}$$

$$\omega_2 = \Omega \sin \theta$$

$$\bar{\Gamma} = I_3 \Omega \cos \theta \hat{x}_3 + I \Omega \sin \theta \hat{x}_2$$

(13,10) með

$$I_1 = I_2, \dot{\omega}_3 = 0$$

$$\omega_1 = 0, \dot{\omega}_2 = 0$$

$$\left. \begin{aligned} I \ddot{\omega}_1 - (I - I_3) \omega_2 \omega_3 &= N_1 \\ &= 0 \end{aligned} \right\} \rightarrow - (I - I_3) \omega_2 \omega_3 = N_1$$

Dæmi 4

(11)

Línum á kartískt hnítakerfi. Notið horn Eulers til að finna eitt mögulegt val fyrir snúning frá (1,0,0) yfir í einingavigurinn n sem liggur mitt á milli jákvæðu hluta x-, y- og z-ásanna. Finnið snúningsfylkin og sannreynið niðurstöðuna. Hvert er hornið frá n niður á hvern ásann x, y eða z?

Frá DC jöfnu (13.83) fáum við

$$\text{því } n = (1,1,1)/\sqrt{3}$$

$$\cos \phi \cos \psi - \sin \phi \cos \theta \sin \psi = \frac{1}{\sqrt{3}}$$

$$-\cos \phi \sin \psi - \sin \phi \cos \theta \cos \psi = \frac{1}{\sqrt{3}}$$

$$\sin \phi \sin \theta = \frac{1}{\sqrt{3}}$$

Við höfum nokkuð frelsi, svo ég vel að reyna

$$\phi = -\frac{\pi}{4}$$

$$\begin{cases} \cos \psi + \cos \theta \sin \psi = \frac{\sqrt{2}}{3} \\ -\sin \psi + \cos \theta \cos \psi = \frac{\sqrt{2}}{3} \end{cases}$$

$$\text{og } \sin \theta = -\sqrt{\frac{2}{3}}$$

$$-(I - I_3) \Omega^2 \cos \theta \sin \theta = N_1 = Mgl \sin \theta$$

$$\rightarrow -\left(\frac{MR^2}{4} + Ml^2 - \frac{MR^2}{2}\right) \Omega^2 \cos \theta = Mgl$$

$$\rightarrow \left(\frac{MR^2}{4} - Ml^2\right) \Omega^2 \cos \theta = Mgl$$

$$\rightarrow \Omega^2 = \frac{Mgl}{\cos \theta} \frac{1}{\left(\frac{MR^2}{4} - Ml^2\right)} = \frac{4gl}{\cos \theta (R^2 - 4l^2)}$$

$$\rightarrow \Omega = \sqrt{\frac{4gl}{\cos \theta (R^2 - 4l^2)}} \quad + \quad R > 2l$$

(10)

(11)

$$\rightarrow \cos \theta = \sqrt{1 - \frac{2}{3}} = \sqrt{\frac{1}{3}}$$

$$\begin{aligned} \text{og } \cos \psi + \frac{1}{\sqrt{3}} \sin \psi &= \sqrt{\frac{2}{3}} \\ -\sin \psi + \frac{1}{\sqrt{3}} \cos \psi &= \sqrt{\frac{2}{3}} \end{aligned} \quad \rightarrow \begin{aligned} \cos \psi &= \frac{1 + \sqrt{3}}{2} \\ \sin \psi &= \frac{1 - \sqrt{3}}{2} \end{aligned}$$

$$\lambda_\phi = \begin{pmatrix} \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\lambda_\theta = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{3}} & -\frac{2}{\sqrt{3}} \\ 0 & \frac{2}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{pmatrix}$$

$$\lambda_\psi = \begin{pmatrix} \frac{1+\sqrt{3}}{2\sqrt{2}} & \frac{1-\sqrt{3}}{2\sqrt{2}} & 0 \\ -\frac{1-\sqrt{3}}{2\sqrt{2}} & \frac{1+\sqrt{3}}{2\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\lambda_\psi \lambda_\theta \lambda_\phi \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{3}}(1, 1, 1)$$

$$\cos \gamma = \frac{1}{\sqrt{3}} \quad \text{hornið niður á ás, } \gamma \sim 54,7^\circ$$

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