

Dæmi 1

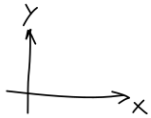
Notum DC (12.36)



$$\vec{F}_r^{eff} = \vec{F} - m\vec{a}_f - m2\vec{\omega} \times \vec{v}_f - m\vec{\omega} \times (\vec{\omega} \times \vec{r}_f) - m\dot{\vec{\omega}} \times \vec{r}_f$$

eingungis kraftur Coriolis skiptir máli hér

$$\vec{N} = -v_0 \hat{e}_y$$



Hnitakerfi samkvæmt mynd 12.7 í DC, kerfi sem snúst með jörðinni

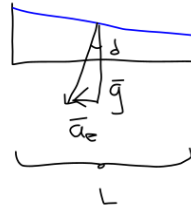
$$\vec{\omega} = \omega \hat{e}_x + \omega \cos \lambda \hat{e}_y + \omega \sin \lambda \hat{e}_z$$

$$\rightarrow \vec{a}_c = 2[-v_0 \hat{e}_y] \times [\hat{e}_z] \omega \sin \lambda = -2v_0 \omega \sin \lambda \hat{e}_x$$

→ hröðun í átt að vesturbakka skurásins

①

ýkt



Yfirborð vatns í stöðugu ástandi verður alltaf þvert á virka þyngdarkraftinn á þess. Köllum hnikunarhornið δ

$$\sin \delta = \frac{a_c}{\sqrt{g^2 + a_c^2}} = \frac{2v_0 \omega \sin \lambda}{\sqrt{g^2 + (2v_0 \omega \sin \lambda)^2}}$$

því má fá fyrir hæðarmun vatnsborðs við bakkana

$$\Delta h = L \sin \delta = \frac{2v_0 L \omega \sin \lambda}{\sqrt{g^2 + (2v_0 \omega \sin \lambda)^2}}$$

$$\omega = 7.3 \cdot 10^{-5} \text{ rad/s}$$

$$g = 9.82 \text{ m/s}^2 \quad L = 50 \text{ m}$$

$$v_0 = 12 \text{ m/s} \quad \lambda = \frac{65^\circ \pi}{180}$$

$$= 0.00308 \text{ m} = \underline{3.08 \text{ mm}}$$

②

Dæmi 2

Notum jöfnur (12.65-67) til að kanna stærðargráður fyrir kúlu skotinni beint í austur með $v_0 = 200 \text{ m/s}$

$$\omega = 7.3 \cdot 10^{-5} \text{ s}^{-1}$$

$$\Delta x' = \frac{\omega g t^3}{3} \cos \lambda - \dot{x}'_0 t$$

$$g = 9.82 \text{ m/s}^2$$

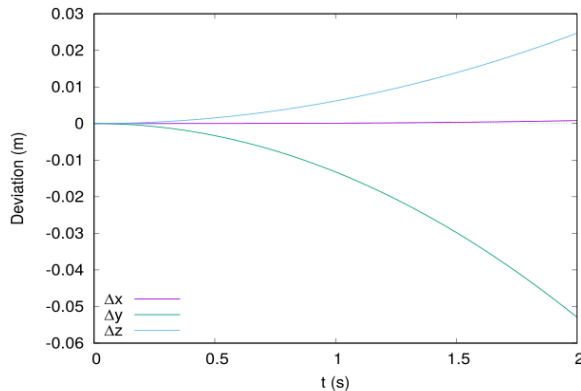
$$\Delta y' = -\omega \dot{x}'_0 t^2 \sin \lambda$$

$$\lambda = \frac{65^\circ \pi}{180}$$

$$\Delta z' = \omega \dot{x}'_0 t^2 \cos \lambda$$

$$\dot{z}'_0 = 0$$

$$\dot{y}'_0 = 0$$



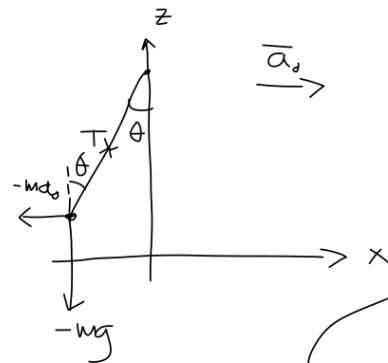
það gleymist oft að kraftur Coriolis veður ekki bara hægri beygju, heldur líka þætti upp á við í þessum aðstæðum

③

Dæmi 3

$$\vec{F}_{eff} = \vec{F} - m\ddot{\vec{r}}_f - m\dot{\vec{\omega}} \times \vec{r}_f - m\vec{\omega} \times (\vec{\omega} \times \vec{r}_f) - 2m\vec{\omega} \times \vec{v}_f$$

a) Föst hröðun \vec{a}_0
finna T og útslag



$$\vec{F}_{eff} = -g\hat{e}_z m - ma_0 \hat{e}_x$$

$$= m(-a_0, 0, -g)$$

$$(z): T \cos \theta = mg$$

$$(x): T \sin \theta = ma_0$$

$$\tan \theta = \frac{a_0}{g} \rightarrow \theta = 0 \text{ et } a_0 = 0$$

④

Eins sést að

$$T^2 \cos^2 \theta + T^2 \sin^2 \theta = (mg)^2 + (m a_0)^2$$

$$\rightarrow T^2 = (mg)^2 + (m a_0)^2$$

$$\rightarrow T = m \sqrt{g^2 + a_0^2}$$

og áður

$$\theta = \arctan\left(\frac{a_0}{g}\right)$$

b) Hringferð með geisla R og fastri ferð v_0

$$\vec{F}_{\text{eff}} = \vec{g} - m \vec{\omega} \times (\vec{\omega} \times \vec{r})$$

Hnitakerfi snýst með farataekinu

$$\rightarrow \ddot{\vec{R}}_f = 0, \vec{v}_r = 0$$

(5)

$$\vec{\omega} = \omega \hat{e}_z$$

$$\vec{F}_{\text{eff}} = -mg \hat{e}_z - m \omega^2 R \hat{e}_x$$

$$T \cos \theta = mg$$

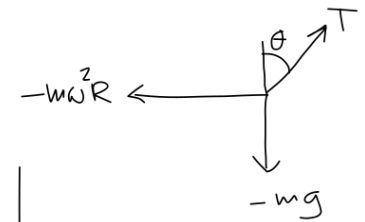
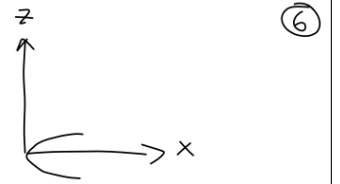
$$T \sin \theta = m \omega^2 R = m \frac{v_0^2}{R}$$

$$\rightarrow \tan \theta = \frac{m v_0^2}{R m g} = \frac{v_0^2}{R g}$$

$$\rightarrow \theta = \arctan\left(\frac{v_0^2}{R g}\right)$$

$$T^2 = (mg)^2 + (m \frac{v_0^2}{R})^2$$

$$\rightarrow T = m \sqrt{g^2 + \frac{v_0^4}{R^2}}$$

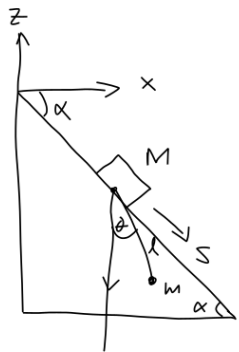


$$v_0 = R \omega$$

$$\rightarrow \omega = \frac{v_0}{R}$$

(6)

Dæmi 4



fyrir M :

$$\begin{cases} x = s \cos \alpha \\ z = -s \sin \alpha \end{cases} \quad \text{Hnit massa}$$

fyrir m :

$$\begin{cases} x = s \cos \alpha + l \sin \theta \\ z = -s \sin \alpha - l \cos \theta \end{cases}$$

Altraðar

$$v_M = \dot{s}$$

$$v_m = (\dot{s} \cos \alpha + l \dot{\theta} \cos \theta, -\dot{s} \sin \alpha + l \dot{\theta} \sin \theta)$$

$$\rightarrow v_m^2 = \dot{s}^2 + (l \dot{\theta})^2 + 2l \dot{s} \dot{\theta} [\cos \alpha \cos \theta - \sin \alpha \sin \theta]$$

$$= \dot{s}^2 + (l \dot{\theta})^2 + 2l \dot{s} \dot{\theta} \cos(\theta + \alpha)$$

(7)

$$T = \frac{M}{2} v_M^2 + \frac{m}{2} v_m^2, \quad U = M g z_M + m g z_m$$

$$\rightarrow L = \frac{M}{2} \dot{s}^2 + \frac{m}{2} [\dot{s}^2 + (l \dot{\theta})^2 + 2l \dot{s} \dot{\theta} \cos(\theta + \alpha)]$$

$$+ M g s \sin \alpha + m g [s \sin \alpha + l \cos \theta]$$

Tvö alnit, s og θ

$$\frac{\partial L}{\partial s} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{s}} \right) = 0$$

$$M g \sin \alpha + m g \sin \alpha - \frac{d}{dt} [M \dot{s} + m \dot{s} + m l \dot{\theta} \cos(\theta + \alpha)] = 0$$

$$\rightarrow g(M+m) \sin \alpha - (M+m) \ddot{s} - m l \ddot{\theta} \cos(\theta + \alpha) + m l \dot{\theta}^2 \sin(\theta + \alpha) = 0$$

(8)

$$(M+m)\ddot{s} + ml\{\ddot{\theta}\cos(\theta+\alpha) - \dot{\theta}^2\sin(\theta+\alpha)\} - g(M+m)\sin\alpha = 0$$

$$\frac{\partial L}{\partial \theta} - \frac{d}{dt}\left(\frac{\partial L}{\partial \dot{\theta}}\right) = 0$$

$$-ml\dot{s}\dot{\theta}\sin(\theta+\alpha) - mgl\sin\theta - \frac{d}{dt}\{ml\dot{s}\cos(\theta+\alpha) - ml\dot{\theta}\} = 0$$

$$-ml\dot{s}\dot{\theta}\sin(\theta+\alpha) - mgl\sin\theta - ml\ddot{s}\cos(\theta+\alpha) + ml\dot{s}\dot{\theta}\sin(\theta+\alpha) - ml\dot{\theta} = 0$$

$$ml\dot{\theta} + ml\ddot{s}\cos(\theta+\alpha) + mgl\sin\theta = 0$$

$$l\ddot{\theta} + \ddot{s}\cos(\theta+\alpha) + g\sin\theta = 0$$

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Smáar sveiflur, fyrst jafnvægisstaða? $\rightarrow \ddot{\theta} = 0, \dot{\theta} = 0$

$$\textcircled{1} \rightarrow \ddot{s} - g\sin\alpha = 0$$

$$\textcircled{2} \rightarrow \ddot{s}\cos(\theta+\alpha) + g\sin\theta = 0$$

$$g\sin\alpha\cos(\theta+\alpha) + g\sin\theta = 0$$

$$\rightarrow \theta_0 = -\alpha \quad (\text{og } \theta_0 = \pi - \alpha) \leftarrow \text{östæðug}$$

$$\rightarrow \theta = \theta_0 + \delta = -\alpha + \delta$$

til að kanna smáar sveiflur

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Setjum inn í hreyfijöfnur

$$(M+m)\ddot{s} + ml\{\ddot{\delta}\cos(\delta) - \dot{\delta}^2\sin(\delta)\} - g(M+m)\sin\alpha = 0$$

$$(M+m)\ddot{s} + ml\left\{\ddot{\delta}\left(1 - \frac{\delta^2}{2}\right) - \dot{\delta}^2\left(\delta - \frac{\delta^3}{6}\right)\right\} - g(M+m)\sin\alpha = 0$$

$$l\ddot{\delta} + \dot{s}\left(1 - \frac{\delta^2}{2}\right) + g\sin(-\alpha + \delta) = 0$$

$$\rightarrow l\ddot{\delta} + \dot{s}\left(1 - \frac{\delta^2}{2}\right) + g\{-\sin\alpha\cos\delta + \cos\alpha\sin\delta\} = 0$$

þá línulega

$$l\ddot{\delta} + \dot{s} - g\sin\alpha + g\cos\alpha \cdot \delta = 0$$

$$(M+m)\ddot{s} + ml\ddot{\delta} - g(M+m)\sin\alpha = 0$$

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Útbúum nýja breytu

$$\ddot{z} \equiv \ddot{s} - g\sin\alpha$$

til að fá línulega afleiðujöfnuhneppið

$$l\ddot{\delta} + \ddot{z} + g\cos\alpha \cdot \delta = 0$$

$$(M+m)\ddot{z} + ml\ddot{\delta} = 0$$

þetta er annarsstigs afleiðuhneppi, og við lærum í síðasta hluta námskeiðsins að eiga við þau, en hér nýtum við okkur að þetta er einfalt vegna seinni jöfnunar

$$l\ddot{\delta} - \frac{ml}{M+m}\ddot{\delta} + g\cos\alpha \cdot \delta = 0$$

$$\ddot{\delta} + \frac{g}{l} \frac{\cos\alpha}{\left(\frac{M}{M+m}\right)} \delta = 0$$

$$\omega = \sqrt{\frac{g\cos\alpha}{l} \frac{M+m}{M}}$$

$$= \sqrt{\frac{g\cos\alpha}{l} \left(1 + \frac{m}{M}\right)}$$

svo er í raun annar sveifluháttur, en vegna útlits seinni jöfnunar er þar $\omega = 0$, skoðum aftur seinna

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