

### Dæmi 1

$$L'(q, \dot{q}, t) = L(q, \dot{q}, t) + \frac{d}{dt} F(q, t)$$

Höfum sýnt að

$$\frac{\partial L}{\partial q} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) = 0$$

$L'$  er fall af sömu breytum og  $L$

$$\rightarrow \frac{\partial L'}{\partial q} - \frac{d}{dt} \left( \frac{\partial L'}{\partial \dot{q}} \right) = 0 \quad \text{ætti að gilda}$$

Sannreynum

$$\begin{aligned} \frac{\partial L'}{\partial q} &= \frac{\partial L}{\partial q} + \frac{\partial}{\partial q} \left( \frac{dF}{dt} \right) \\ \frac{\partial L'}{\partial \dot{q}} &= \frac{\partial L}{\partial \dot{q}} + \frac{\partial}{\partial \dot{q}} \left( \frac{dF}{dt} \right) \end{aligned} \quad \rightarrow \frac{d}{dt} \left( \frac{\partial L'}{\partial \dot{q}} \right) = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) + \frac{d}{dt} \left[ \frac{\partial}{\partial \dot{q}} \left( \frac{dF}{dt} \right) \right] \quad (*)$$

①

Athugum heildaraflejuna af  $F$

$$\frac{dF}{dt} = \frac{\partial F}{\partial q} \dot{q} + \frac{\partial F}{\partial t} \quad \rightarrow \quad \frac{\partial}{\partial \dot{q}} \left( \frac{dF}{dt} \right) = \frac{\partial F}{\partial q}$$

$F = F(q, t)$

notum í (\*)

$$\rightarrow \frac{d}{dt} \left( \frac{\partial L'}{\partial \dot{q}} \right) = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) + \frac{d}{dt} \left( \frac{\partial F}{\partial q} \right)$$

$$\begin{aligned} \rightarrow \frac{\partial L'}{\partial q} - \frac{d}{dt} \left( \frac{\partial L'}{\partial \dot{q}} \right) &= \frac{\partial L}{\partial q} + \frac{\partial}{\partial q} \left( \frac{dF}{dt} \right) - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) - \frac{d}{dt} \left( \frac{\partial F}{\partial q} \right) = 0 \\ &= \underbrace{\frac{\partial L}{\partial q} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right)}_{E-L} + \underbrace{\left[ \frac{\partial}{\partial q} \left( \frac{dF}{dt} \right) - \frac{d}{dt} \left( \frac{\partial F}{\partial q} \right) \right]}_{\text{termur } L} = 0 \end{aligned}$$

Dæmi 2 ③ ögn með massa  $m$  hreyfist í kúlufirborði án þess að ytri kraftar verki á hana. (Heimur hennar er kúlufirborð með geisla  $R$ )

Nýtum Ex. 6.3 í DC, og munum að  $R$  er fasti

① 2 alhnit -- yfirborð, hornin úr kúluhnitum spanna það

②  $\rightarrow L = \frac{mR^2}{2} \left[ \dot{\theta}^2 + (\sin^2 \theta) \dot{\phi}^2 \right] = L(\theta, \dot{\phi}, \dot{\theta})$

③ Alskriðþingar

$$P_\theta = \frac{\partial L}{\partial \dot{\theta}} = mR^2 \dot{\theta}$$

ekki fasti, því  $\theta$  kemur fyrir í  $L$

$$P_\phi = \frac{\partial L}{\partial \dot{\phi}} = mR^2 (\sin^2 \theta) \dot{\phi}$$

fasti, því  $\phi$  er rásuð breyta

②

Fall Hamiltons

$$\begin{aligned} H &= P_\theta \dot{\theta} + P_\phi \dot{\phi} - L = \frac{mR^2}{2} \left[ \dot{\theta}^2 + (\sin^2 \theta) \dot{\phi}^2 \right] \\ &= \frac{P_\theta^2}{2mR^2} + \frac{P_\phi^2}{2mR^2 \sin^2 \theta} = H(P_\theta, P_\phi, \theta) \end{aligned}$$

í raun sést hér að  $H$  og  $L$  eru bæði einfaldilega  $T$  í mismunandi breytum

④ Hreyfijöfnur Hamiltons

$$\dot{\theta} = - \frac{\partial H}{\partial P_\theta} = \frac{1}{mR^2} \frac{P_\phi \cos \theta}{\sin^3 \theta}$$

$$\dot{\phi} = - \frac{\partial H}{\partial P_\phi} = 0$$

$$\dot{\theta} = \frac{\partial H}{\partial P_\theta} = \frac{P_\phi}{mR^2}$$

$$\dot{\phi} = \frac{\partial H}{\partial P_\phi} = \frac{P_\phi}{mR^2 \sin^2 \theta}$$

④

þetta 1. sigs hreyfijöfnuhneppi er mjög heppilegt beint í tölulega reikninga. Hægt er að sýna að hreyfing agnarinnar er alltaf eftir stórhring, en ég sleppti að biðja um það hér.

(5)

Ögnin finnur fyrir engu ytra mætti. Fall Hamiltons er einungis hreyfiorkan. Enginn núningskraftur vinnur á móti hreyfingunni, Fall Hamiltons er ekki háð tíma, þess vegna er fall Hamiltons hér heildarorka agnarinnar.

(5)

Dæmi 3  
Ögn með massa  $m$  hreyfist í yfirborði sem myndast þegar fleygboga er snúið um z-ás kartísks hnítakerfis. Yfirborðið er kyrrt í þyngdarsviði. Notið sívalningshnitin  $r$  (mælt frá samhverfuás yfirborðsins z-ásum) og  $\phi$  sem alhnit

Notum sívalningshnit  $r, \phi$

$$\rightarrow L = \frac{m}{2} \left[ \dot{r}^2 + r^2 \dot{\phi}^2 + \dot{z}^2 \right] - mgz$$

Fleygbogayfirborð  $rz = r^2 = x^2 + y^2$

$$z = \frac{r^2}{a} \rightarrow \dot{z} = \frac{2r\dot{r}}{a}$$

$$\begin{aligned} \rightarrow L &= \frac{m}{2} \left[ \dot{r}^2 + r^2 \dot{\phi}^2 + \frac{4r^2}{a^2} \dot{r}^2 \right] - mg \frac{r^2}{a} \\ &= \frac{m}{2} \left[ \dot{r}^2 \left( 1 + \frac{4r^2}{a^2} \right) + (\dot{r}\phi)^2 \right] - mg \frac{r^2}{a} = L(r, \dot{r}, \phi) \end{aligned}$$

(2) Alskráðungar og  $H$

$$P_\phi = \frac{\partial L}{\partial \dot{\phi}} = mr^2 \dot{\phi} = \text{fostur} \quad \text{því } \phi \text{ er rásuð breyta}$$

$$P_r = \frac{\partial L}{\partial \dot{r}} = m\dot{r} \left[ 1 + \frac{4r^2}{a^2} \right]$$

$$\begin{aligned} H &= P_\phi \dot{\phi} + P_r \dot{r} - L = mr^2 \dot{\phi}^2 - \frac{m}{2} r^2 \dot{\phi}^2 + m\dot{r}^2 \left[ 1 + \frac{4r^2}{a^2} \right] \\ &\quad - \frac{m}{2} \dot{r}^2 \left[ 1 + \frac{4r^2}{a^2} \right] + mg \frac{r^2}{a} \end{aligned}$$

$$= \frac{P_r^2}{2m \left[ 1 + \frac{4r^2}{a^2} \right]} + \frac{P_\phi^2}{2mr^2} + mg \frac{r^2}{a}$$

(7)

(3) Hreyfijöfnur Hamiltons

$$\dot{r} = \frac{\partial H}{\partial P_r} = \frac{P_r}{m \left[ 1 + \frac{4r^2}{a^2} \right]}$$

$$\dot{P}_r = -\frac{\partial H}{\partial r} = -2mg \frac{r}{a} + \frac{P_r^2}{mr^3} + \frac{P_r^2 \frac{8r}{a^2}}{2m \left[ 1 + \frac{4r^2}{a^2} \right]^2}$$

$$\dot{\phi} = \frac{\partial H}{\partial P_\phi} = \frac{P_\phi}{mr^2}$$

$$\dot{P}_\phi = -\frac{\partial H}{\partial \phi} = 0$$

$\phi$  er rásuð breyta

(6)

$$(4) L = \frac{m}{2} \left\{ \dot{r}^2 \left( 1 + \frac{4r^2}{\alpha^2} \right) + r^2 \dot{\phi}^2 \right\} - mg \frac{r^2}{\alpha}$$

$$\frac{\partial L}{\partial r} - \frac{1}{dt} \left( \frac{\partial L}{\partial \dot{r}} \right) = 0$$

$$\hookrightarrow \frac{m}{2} \dot{r}^2 \frac{8r}{\alpha^2} + m r \dot{\phi}^2 - 2mg \frac{r}{\alpha} - \frac{d}{dt} \left\{ m \dot{r} \left( 1 + \frac{4r^2}{\alpha^2} \right) \right\} = 0$$

$$\rightarrow \dot{r}^2 \frac{4r}{\alpha^2} + r \dot{\phi}^2 - 2g \frac{r}{\alpha} - \dot{r} \left( 1 + \frac{4r^2}{\alpha^2} \right) - \frac{\dot{r} \cdot 8r \dot{r}}{\alpha^2} = 0$$

$$\rightarrow \boxed{\dot{r} \left( 1 + \frac{4r^2}{\alpha^2} \right) + \frac{4r \dot{r}^2}{\alpha^2} - r \dot{\phi}^2 + 2g \frac{r}{\alpha} = 0}$$

(9)

(5) Finnið tæni smárra sveifla agnarinnar þegar  $d\phi/dt = 0$   
Hér væri hægt að nota hreyfijöfnuna í síðasta lið, en ég stytta mér leis

$$\frac{d\phi}{dt} = 0 \rightarrow P_\phi = 0 \rightarrow H = \frac{P_r^2}{2m \left[ 1 + \frac{4r^2}{\alpha^2} \right]} + \frac{mg}{\alpha} r^2$$

Við pekkjum fall Hamiltons fyrir hreintóna sveifil

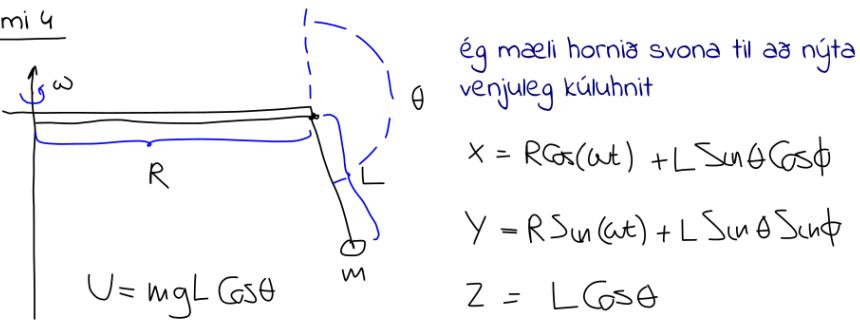
$$H = \frac{P_r^2}{2m} + \frac{m}{2} \omega^2 q^2$$

Athugun á okkar H sýnir að það lýsi línulegum sveifli ef  $\frac{r^2}{\alpha^2} \ll 1$

$$\rightarrow H \rightarrow \approx \frac{P_r^2}{2m} + \frac{mg}{\alpha} r^2$$

$$\rightarrow \frac{mg}{\alpha^2} = \frac{1}{2} m \omega^2 \rightarrow \boxed{\omega = \sqrt{\frac{2g}{\alpha}}}$$

Dæmi 4



$$\dot{x} = -\omega R \sin(\omega t) + L \dot{\theta} \cos \theta \cos \phi - L \dot{\phi} \sin \theta \sin \phi$$

$$\dot{y} = \omega R \cos(\omega t) + L \dot{\theta} \cos \theta \sin \phi + L \dot{\phi} \sin \theta \cos \phi$$

$$\ddot{z} = -\dot{\theta} L \sin \theta$$

$$T = \frac{m}{2} \left\{ \dot{x}^2 + \dot{y}^2 + \dot{z}^2 \right\}$$

(10)

$$T = \frac{m}{2} \left\{ L^2 \dot{\theta}^2 + (L \sin \theta \cdot \dot{\phi})^2 + \omega^2 R^2 [\sin^2(\omega t) + \cos^2(\omega t)] \right\}$$

$$+ 2\omega RL (-\sin(\omega t) \cos \theta \cos \phi \cdot \dot{\theta} + \sin(\omega t) \sin \theta \sin \phi \cdot \dot{\phi})$$

$$+ 2\omega RL (\cos(\omega t) \cos \theta \sin \phi \cdot \dot{\theta} + \cos(\omega t) \sin \theta \cos \phi \cdot \dot{\phi}) \right]$$

$$\rightarrow L = \frac{m}{2} \left\{ (L \dot{\theta})^2 + (L \sin \theta \cdot \dot{\phi})^2 + (\omega R)^2 \right. \\ \left. + \dot{\theta} 2\omega RL \cos \theta \sin(\phi - \omega t) + \dot{\phi} 2\omega RL \sin \theta \cos(\phi - \omega t) \right\} - mgL \cos \theta$$

$$\frac{\partial L}{\partial \theta} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\theta}} \right) = 0$$

$$\rightarrow mL^2 \sin \theta \cos \theta \cdot \ddot{\phi} + mgL \sin \theta - \dot{\theta}^2 w_{RL} \sin \theta \sin(\phi - \omega t)$$

$$+ \dot{\phi} 2w_{RL} \cos \theta \cos(\phi - \omega t)$$

$$- \frac{d}{dt} \left\{ mL^2 \ddot{\theta} + 2w_{RL} \cos \theta \sin(\phi - \omega t) \right\} = 0$$

$$= \ddot{\phi} mL^2 \sin \theta \cos \theta + mgL \sin \theta - \dot{\theta} 2w_{RL} \sin \theta \sin(\phi - \omega t)$$

$$+ \dot{\phi} 2w_{RL} \cos \theta \cos(\phi - \omega t)$$

$$- mL^2 \ddot{\theta} + 2w_{RL} \dot{\theta} \sin \theta \sin(\phi - \omega t)$$

$$- 2w_{RL} \cos \theta \cos(\phi - \omega t) \cdot (\dot{\phi} - \omega)$$

(13)

$$\ddot{\phi} - \dot{\phi}^2 \sin \theta \cos \theta - 2w_{RL}^2 \cos \theta \cos(\phi - \omega t) - \frac{g}{L} \sin \theta = 0$$

(14)

$$\frac{\partial L}{\partial \dot{\phi}} - \frac{d}{dt} \left( \frac{\partial L}{\partial \ddot{\phi}} \right) = 0$$

...

$$\ddot{\phi} + 2\cot \theta \cdot \dot{\phi}^2 + \frac{2w_{RL}^2 R}{mL} \frac{\sin(\phi - \omega t)}{\sin \theta} = 0$$

Mér sýnist samanburður við "8.6 Example" í bók DC sýna að þetta verði hreyfijöfnurnar þegar  $\omega = 0$ , en það þarf að beita einni tímaafleiðu til að sjá það fyrir þessa seinni jöfnu. Það er athyglisvert að snúningur stangarinnar kemur eins og þvingunarliður. Því er öruggt að H lýsir ekki heildarorku kerfisins, þetta er í raun opí kerfi, þar sem snúningurinn bætir við og tekur út orku