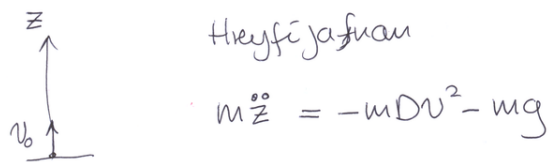


# 1. Demokramtur

(1)

Bolta heit seint upp með ferð  $v_0$  í föstu þyngðarsviði.  
 Hverjee langt upp fer hann. Þrögnkraftur  
 $f \sim v^2$



Vegna þrögnkrafts er leppilegt að umrita fyrir  $v$   
 í stað  $z$

$$\ddot{z} = \frac{dz}{dt} = \frac{d}{dt} \left[ \frac{dz}{dt} \right] = \frac{dv}{dt} = \frac{dv}{dz} \frac{dz}{dt} = v \frac{dv}{dz}$$

Hreyfijafnan er þú

(2)

$$m v \frac{dv}{dz} = -m Dv^2 - mg$$

$$\rightarrow \frac{v dv}{Dv^2 + g} = -dz$$

$$\int_{v_0}^v \frac{v' dv'}{D(v')^2 + g} = - \int_0^z dz' \rightarrow \frac{1}{2D} \ln(Dv^2 + g) \Big|_{v_0}^v = -z$$

$$\rightarrow z = - \frac{1}{2D} \ln \left\{ \frac{Dv^2 + g}{Dv_0^2 + g} \right\} = \frac{1}{2D} \ln \left\{ \frac{Dv_0^2 + g}{Dv^2 + g} \right\}$$

Hæsti punkturinn er þegar  $v = 0$

$$\rightarrow z_{\max} = \frac{1}{2D} \ln \left\{ \frac{Dv_0^2 + g}{g} \right\}$$

$$z_{\max} = \frac{1}{2D} \ln \left\{ \frac{Dv_0^2}{g} + 1 \right\}$$

$$= \frac{1}{2D} \left\{ \frac{Dv_0^2}{g} - \frac{(Dv_0^2)^2}{2g^2} + o(D^3) \right\}$$

best er graf af (3)

$$\frac{2z_{\max} g}{v_0^2} = \frac{g}{Dv_0^2} \ln \left\{ \frac{Dv_0^2}{g} + 1 \right\}$$

$$[D] = \frac{1}{L}$$

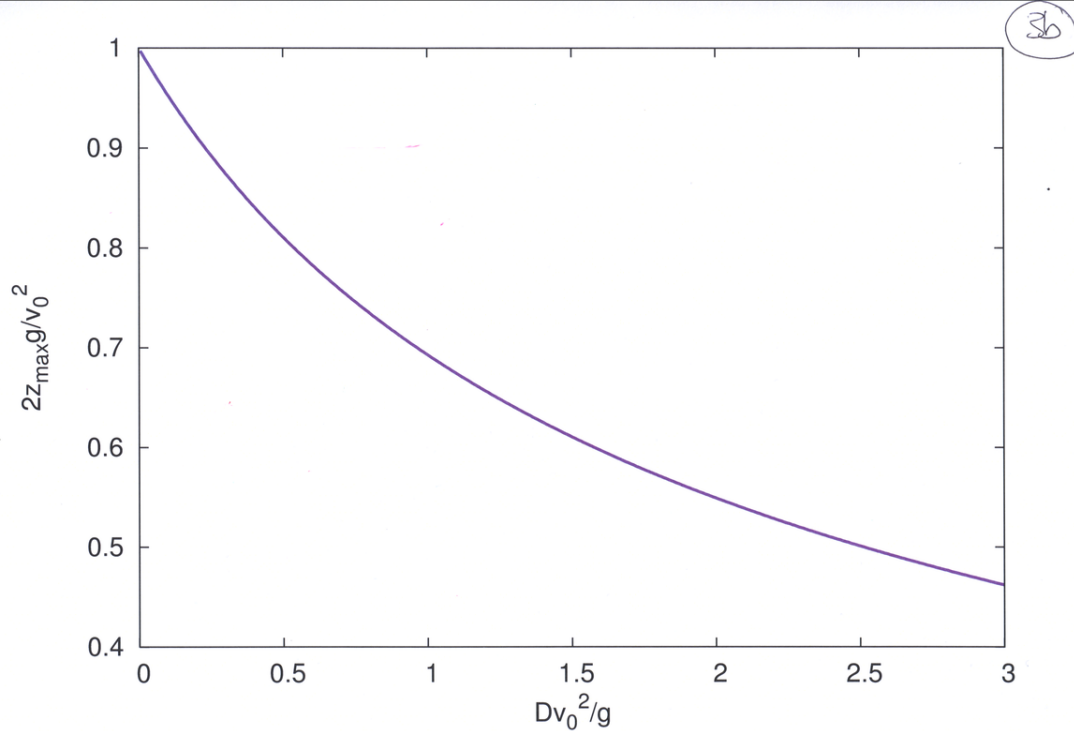
$$\rightarrow \left[ \frac{Dv_0^2}{g} \right] = 1$$

$$\text{og } \frac{2z_{\max} g}{v_0^2} (D \rightarrow 0) = 1$$

$$\rightarrow z_{\max} (D \rightarrow 0) = \frac{v_0^2}{2g}$$

(2) Kraftur  $\vec{a}$  ögu í kúluknitum  $F(r, \theta, \phi)$   
 Hvernig er hreyfijafnan?

Vandinn hér er að  $\hat{r}, \hat{\theta}$  og  $\hat{\phi}$  eru túmaladdir, það  $\vec{a}$   
 ekki við fyrir kortest hnit Sjá (1.14) í bók



(3)

Stöðsetning og norðinnar er  $\vec{r} = r\hat{e}_r$  þá  $r\hat{r}$   
þú er hreyfingunni kemur

$$m\ddot{\vec{r}} = \vec{F}$$

$$\vec{v} = \dot{\vec{r}} = \dot{r}\hat{e}_r + r\dot{\hat{e}}_r$$

Vitum að einingarröðunir  $\hat{e}_r, \hat{e}_\theta, \hat{e}_\phi$  eru  
öndver títla  $\rightarrow$  löðun

$$\hat{e}_r = \hat{e}_1 \sin\theta \cos\phi + \hat{e}_2 \sin\theta \sin\phi + \hat{e}_3 \cos\theta$$

$$\hat{e}_\theta = \hat{e}_1 \cos\theta \cos\phi + \hat{e}_2 \cos\theta \sin\phi - \hat{e}_3 \sin\theta$$

$$\hat{e}_\phi = -\hat{e}_1 \sin\phi + \hat{e}_2 \cos\phi$$

$$\rightarrow \dot{\hat{e}}_r = \hat{e}_1 \left\{ \dot{\theta} \cos\theta \cos\phi - \dot{\phi} \sin\theta \sin\phi \right\} + \hat{e}_2 \left\{ \dot{\theta} \cos\theta \sin\phi + \dot{\phi} \sin\theta \cos\phi \right\} - \hat{e}_3 \left\{ \dot{\theta} \sin\theta \right\}$$

(4)

$$\rightarrow \dot{\hat{e}}_r = \hat{e}_\theta \dot{\theta} + \hat{e}_\phi \dot{\phi} \sin\theta$$

eins fast

$$\dot{\hat{e}}_\theta = -\hat{e}_r \dot{\theta} + \hat{e}_\phi \dot{\phi} \cos\theta$$

$$\dot{\hat{e}}_\phi = -\hat{e}_r \dot{\phi} \sin\theta - \hat{e}_\theta \dot{\phi} \cos\theta$$

$$\rightarrow \vec{v} = \dot{\vec{r}} = \dot{r}\hat{e}_r + r\dot{\hat{e}}_r = \dot{r}\hat{e}_r + r\dot{\hat{e}}_\theta \dot{\theta} + r\dot{\hat{e}}_\phi \dot{\phi} \sin\theta$$

$$\vec{a} = \dot{\vec{v}} = \ddot{r}\hat{e}_r + \dot{r}\dot{\hat{e}}_r + \dot{r}\dot{\hat{e}}_\theta \dot{\theta} + r\dot{\hat{e}}_\theta \ddot{\theta}$$

$$+ r\dot{\hat{e}}_\theta \ddot{\theta} + \dot{r}\dot{\hat{e}}_\phi \dot{\phi} \sin\theta + r\dot{\hat{e}}_\phi \dot{\phi} \ddot{\theta} \sin\theta$$

$$+ r\dot{\hat{e}}_\phi \dot{\phi} \ddot{\theta} \cos\theta + r\dot{\hat{e}}_\phi \ddot{\phi} \sin\theta$$

(5)

$$\vec{a} = \ddot{r}\hat{e}_r + \dot{r} \left\{ \dot{\hat{e}}_\theta \dot{\theta} + \dot{\hat{e}}_\phi \dot{\phi} \sin\theta \right\} + r\dot{\hat{e}}_\theta \ddot{\theta}$$

$$+ r \left\{ -\hat{e}_r \dot{\theta} + \hat{e}_\phi \dot{\phi} \cos\theta \right\} \dot{\theta} + r\dot{\hat{e}}_\theta \ddot{\theta} + r\dot{\hat{e}}_\phi \dot{\phi} \ddot{\theta} \sin\theta$$

$$+ r \left\{ -\hat{e}_r \dot{\phi} \sin\theta - \hat{e}_\theta \dot{\phi} \cos\theta \right\} \dot{\phi} \sin\theta + r\dot{\hat{e}}_\phi \dot{\phi} \ddot{\theta} \cos\theta + r\dot{\hat{e}}_\phi \ddot{\phi} \sin\theta$$

$$\vec{a} = \hat{e}_r \left[ \ddot{r} - r\dot{\theta}^2 - r\dot{\phi}^2 \sin^2\theta \right] + \hat{e}_\theta \left[ r\ddot{\theta} + 2\dot{r}\dot{\theta} - r\dot{\phi}^2 \cos\theta \sin\theta \right]$$

$$+ \hat{e}_\phi \left[ r\dot{\phi} \sin\theta + 2\dot{r}\dot{\phi} \sin\theta + 2r\dot{\theta} \dot{\phi} \cos\theta \right]$$

$$= \frac{1}{m} \left\{ \hat{e}_r F_r + \hat{e}_\theta F_\theta + \hat{e}_\phi F_\phi \right\}$$

(6)

(3) Bæt ytt af ~~stöð~~ ~~með~~  $v_0$ ,  $F = -F_0 e^{+\beta v}$  viðnamskr.

Hreyfingunni  $ma = m\ddot{x} = m\dot{v} = -F_0 e^{+\beta v}$

$$\rightarrow m \frac{dv}{dt} + F_0 e^{+\beta v} = 0, \quad v(0) = v_0$$

Ágemanleg afleiðunni

$$dt = -\frac{m}{F_0} e^{-\beta v} dv \rightarrow \int_0^t dt' = -\frac{m}{F_0} \int_{v_0}^{v(t)} dv e^{-\beta v}$$

$$\rightarrow t = +\frac{m}{F_0 \beta} \left\{ e^{-\beta v(t)} - e^{-\beta v_0} \right\}$$

$$+ \left\{ \frac{F_0 \beta t}{m} + e^{-\beta v_0} \right\} = +e^{-\beta v(t)} \rightarrow -\beta v(t) = \ln \left\{ \frac{F_0 \beta t}{m} + e^{-\beta v_0} \right\}$$

(7)

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$$v(t) = -\frac{1}{\beta} \ln \left\{ \frac{F_0 \beta t}{m} + e^{-\beta v_0} \right\}$$

finnum  $t_m$  peger  $v(t_m) = 0$

$$0 = -\frac{1}{\beta} \ln \left\{ \frac{F_0 \beta t_m}{m} + e^{-\beta v_0} \right\}$$

$$\ln(1) = 0 \rightarrow \frac{F_0 \beta t_m}{m} + e^{-\beta v_0} = 1$$

ada  $t_m = \frac{m}{F_0 \beta} \{ 1 - e^{-\beta v_0} \}$

max timum, en segum efi ad finna vegalegdina

$$\frac{dx}{dt} = -\frac{1}{\beta} \ln \left\{ \frac{F_0 \beta t}{m} + e^{-\beta v_0} \right\}$$

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$$\int_0^x dx' = -\frac{1}{\beta} \int_0^t dt' \ln \left\{ \frac{F_0 \beta t'}{m} + e^{-\beta v_0} \right\}$$

notum  $\int dx \ln(a+bx) = \left\{ x + \frac{a}{b} \right\} \ln(a+bx) - x$  (GR: 2.7.29)

(ada maxima, en fa part ad hunda einum autafala)

$$x = -\frac{1}{\beta} \left\{ \left[ t + \frac{e^{-\beta v_0} m}{F_0 \beta} \right] \ln \left\{ e^{-\beta v_0} + \frac{F_0 \beta t}{m} \right\} - t - \frac{e^{-\beta v_0} m}{F_0 \beta} (-\beta v_0) \right\}$$

$$= -\frac{1}{\beta} \left\{ \left[ t + \frac{e^{-\beta v_0} m}{F_0 \beta} \right] \ln \left[ e^{-\beta v_0} + \frac{F_0 \beta t}{m} \right] - t + \frac{e^{-\beta v_0} m}{F_0 \beta} \beta v_0 \right\}$$

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Vegalegdin varðer  $x(t_m)$

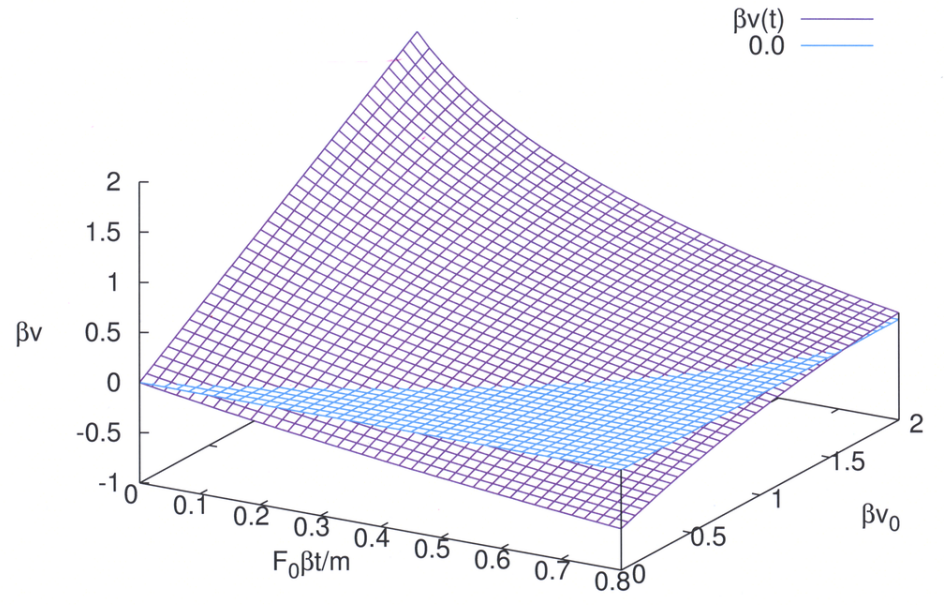
$$x(t_m) = -\frac{1}{\beta} \left\{ \frac{m}{F_0 \beta} \ln \left[ e^{-\beta v_0} + 1 - e^{-\beta v_0} \right] - \frac{m}{F_0 \beta} \left[ 1 - e^{-\beta v_0} \right] + \frac{m}{F_0 \beta} e^{-\beta v_0} \beta v_0 \right\}$$

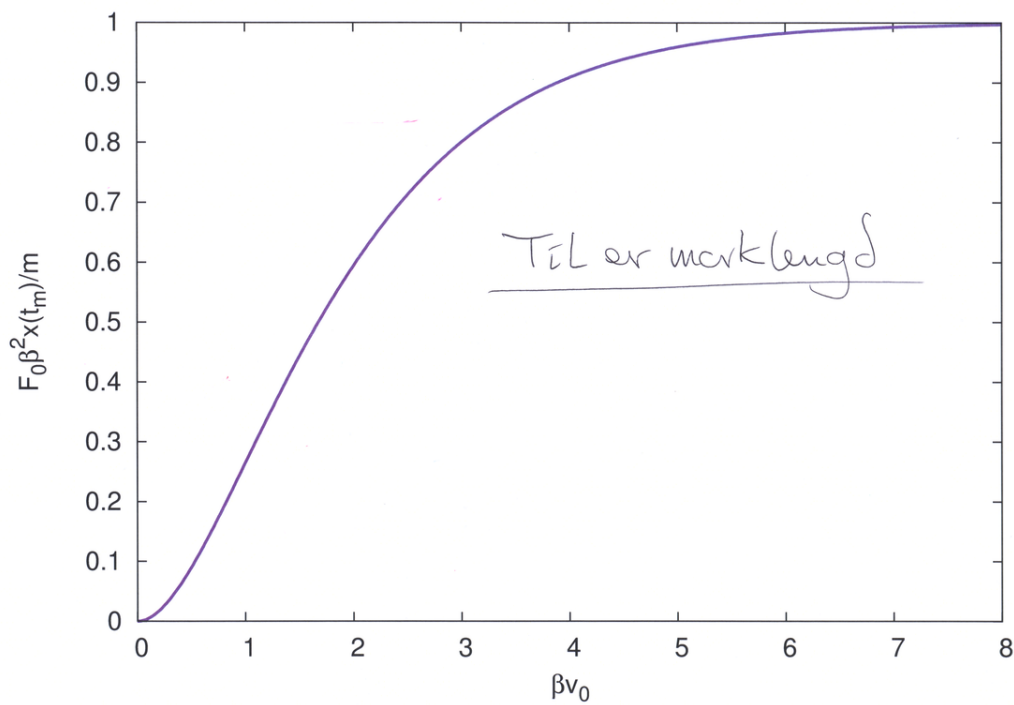
$$x(t_m) = +\frac{m}{\beta^2 F_0} \left[ 1 - e^{-\beta v_0} (1 + \beta v_0) \right]$$

Gröf  $\beta v(t) = -\ln \left\{ \frac{F_0 \beta t}{m} + e^{-\beta v_0} \right\} \rightarrow \beta v$

$\frac{F_0 \beta^2}{m} x(t_m) = \left\{ 1 - e^{-\beta v_0} (1 + \beta v_0) \right\} \rightarrow \frac{F_0 \beta^2}{m} x$

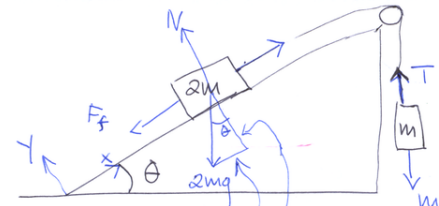
11





(12)

(4)



fyrir hveða  $\theta$  fast  
 Jafur hveði fyrir massana

(13)

$$mg - T = ma$$

$$\rightarrow T = m(g - a)$$

y-límt:  $N - 2mg \cos \theta = m\ddot{y} = 0$

$$\rightarrow N = 2mg \cos \theta$$

x-límt:  $T - 2mg \sin \theta - 2\mu_k mg \cos \theta = ma$

Við leitum að  $\theta_0$  sem gefur  $a = 0$

$$\rightarrow (g - a) - 2g \sin \theta_0 - 2\mu_k g \cos \theta_0 = 0$$

(14)

$$g - 2g \sin \theta_0 - 2\mu_k g \cos \theta_0 = 0$$

$$\frac{1}{2} - \sin \theta_0 - \mu_k \cos \theta_0 = 0$$

$$\frac{1}{2} - \sin \theta_0 - \mu_k \sqrt{1 - \sin^2 \theta_0} = 0$$

$$\frac{1}{2} - \sin \theta_0 = \mu_k \sqrt{1 - \sin^2 \theta_0} \rightarrow \left(\frac{1}{2} - \sin \theta_0\right)^2 = \mu_k^2 (1 - \sin^2 \theta_0)$$

$$\rightarrow \sin^2 \theta_0 + \frac{1}{4} - \sin \theta_0 = \mu_k^2 (1 - \sin^2 \theta_0)$$

$$(1 + \mu_k^2) \sin^2 \theta_0 - \sin \theta_0 + \left(\frac{1}{4} - \mu_k^2\right) = 0$$

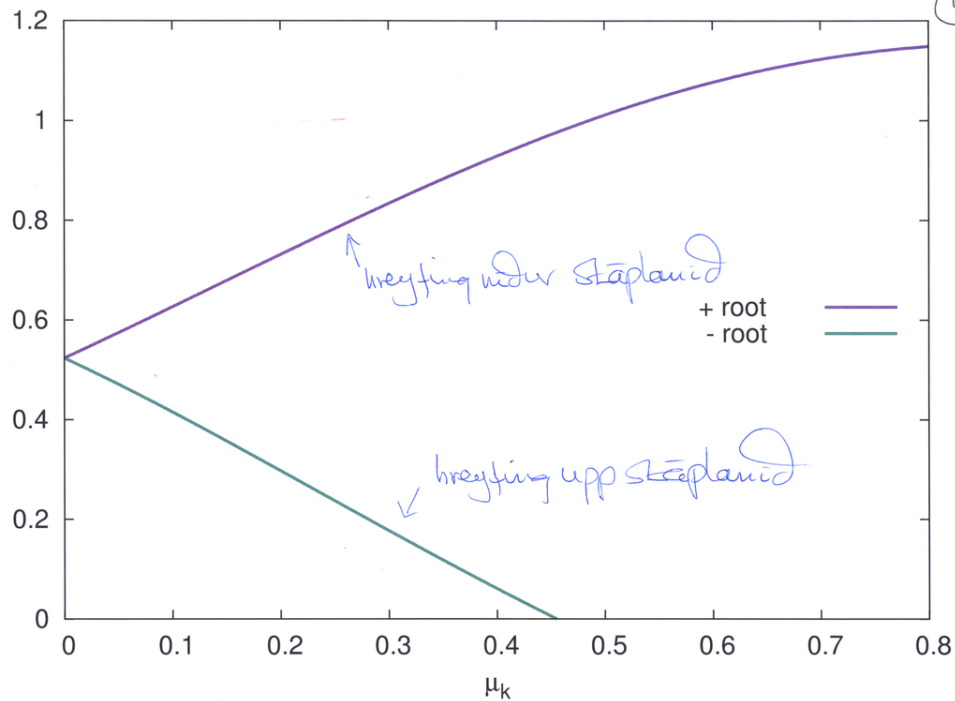
$$\rightarrow \sin \theta_0 = \frac{1 \pm \sqrt{1 - 4(1 + \mu_k^2)\left(\frac{1}{4} - \mu_k^2\right)}}{2(1 + \mu_k^2)} = \frac{1 \pm \mu_k \sqrt{3 + 4\mu_k^2}}{2(1 + \mu_k^2)}$$

(15)

$$\theta_0 = \arcsin \left\{ \frac{1 \pm \mu_k \sqrt{3 + 4\mu_k^2}}{2(1 + \mu_k^2)} \right\}$$

því reður

lími stöðvinn þ.s.  $\mu_k$  kemur fyrir  
 hreyfing í tveggjum

$\theta_0$  (rad)

(15)

(5) 2-21 í bók

Kasthreyfing í x-z sléttu

$$\left. \begin{aligned} x &= v_0 t \cos \theta \\ z &= v_0 t \sin \theta - \frac{1}{2} g t^2 \end{aligned} \right\} \vec{r} = x \hat{e}_x + z \hat{e}_z = (v_0 t \cos \theta, 0, v_0 t \sin \theta - \frac{1}{2} g t^2)$$

$$\rightarrow \vec{p} = m \dot{\vec{r}} = m(v_0 \cos \theta, 0, v_0 \sin \theta - g t)$$

$$\vec{L} = \vec{r} \times \vec{p} = (v_0 t \cos \theta, 0, v_0 t \sin \theta - \frac{1}{2} g t^2) \times (v_0 \cos \theta, 0, v_0 \sin \theta - g t)$$

$$\begin{aligned} &= -\hat{e}_y \left\{ v_0^2 t \cos \theta \sin \theta - v_0 t \cos \theta g t - v_0^2 t \sin \theta \cos \theta + v_0 \cos \theta \frac{1}{2} g t^2 \right\} \\ &= \hat{e}_y \frac{1}{2} m g v_0^2 t^2 \cos \theta \end{aligned}$$

$$\rightarrow \dot{\vec{L}} = \hat{e}_y m g v_0 t \cos \theta$$

Krafturinn á öguina í kasthreyfingu er

$$\vec{F} = -m g \hat{e}_z$$

$$\rightarrow \vec{N} = \vec{r} \times \vec{F} = (v_0 t \cos \theta, 0, v_0 t \sin \theta - \frac{1}{2} g t^2) \times (0, 0, -m g)$$

$$= \hat{e}_y \{ + m g v_0 t \cos \theta \}$$

$$\rightarrow \dot{\vec{L}} = \frac{d\vec{L}}{dt} = \vec{N}$$

(17)

(6) Fall í föstu þyngdarsvæði með vörðunskr.  $\sim v^4$ Setjum  $v_0 = 0$ 

$$\begin{array}{l} z \\ \downarrow \\ \text{Hreyfing} \end{array} \quad m \ddot{z} = -m \gamma v^4 + m g$$

$$\text{líns og í dæmi ①} \quad m v \frac{dv}{dz} = -m \gamma v^4 + m g$$

$$\rightarrow \frac{v dv}{-\gamma v^4 + g} = dz \quad \text{þá} \quad \frac{v dv}{\gamma v^4 - g} = -dz$$

Notum GR 2.132.2

$$\int \frac{x dx}{b x^4 + a} = \frac{1}{4i \sqrt{ab}} \ln \left\{ \frac{a + x^2 i \sqrt{ab}}{a - x^2 i \sqrt{ab}} \right\} \quad ab < 0$$

$$\int_0^z dz' = \int_0^v \frac{v' dv'}{-\gamma (v')^4 + g} \rightarrow z = \frac{1}{4 \sqrt{\gamma g}} \ln \left\{ \frac{g + v^2 \sqrt{\gamma g}}{g - v^2 \sqrt{\gamma g}} \right\}$$

(18)

An vidnáms gildir

(19)

$$\ddot{z} = g \rightarrow \dot{z} = v = gt$$

$$\text{og } \frac{v dv}{g} = dz \rightarrow \int_0^v v' dv' = g \int_0^z dz'$$

$$\rightarrow \frac{1}{2} v^2 = gz \rightarrow z = \frac{1}{2} \frac{v^2}{g}$$

$$z = \frac{1}{4\sqrt{rg}} \ln \left\{ \frac{1 + v^2 \frac{r}{g}}{1 - v^2 \frac{r}{g}} \right\} \approx \frac{1}{4\sqrt{rg}} \left[ 2v^2 \frac{r}{g} + \frac{2}{3} \left( \frac{r}{g} \right)^{3/2} v^6 + \dots \right]$$

$$\approx \frac{v^2}{2g} + \frac{v^6}{6} \frac{r}{g^2} + \dots$$

$$F = m \frac{dv}{dt} = mg - mrv^4$$

$$\rightarrow \frac{dv}{-rv^4 + g} = dt$$

Notum GR 2.132.1

$$\int \frac{dx}{bx^4+a} = \frac{\alpha'}{4a} \left\{ \ln \left( \frac{x+\alpha'}{x-\alpha'} \right) + 2 \arctan \left( \frac{x}{\alpha'} \right) \right\}$$

$$\alpha' = \sqrt[4]{-\frac{a}{b}}$$

þú er högt að

linda út  $t = F(v)$

(20)