

Dæmi 1 Ögn með massa m í mættinu $U(x) = U_0 \exp(-kx)$ hreyfist á bilinu $0 \leq x < \infty$, $x(0) = 0$, $x(x) = x_0$

Finnum τ

$$dt = \pm \frac{dx}{\sqrt{\frac{2}{m}(E - U(x))}} = \pm \frac{dx}{\sqrt{\frac{2E}{m} - \frac{2U_0}{m} e^{-kx}}}$$

$$= \pm \frac{dx}{\sqrt{\frac{2U_0}{m} \left(\frac{E}{U_0} - e^{-kx} \right)}}$$

Orkan fyrir kyrrstæða ögn í punktinum $x=0$ er

$$E = 0 + U(0) = U_0 \rightarrow dt = \pm \frac{dx}{\sqrt{\frac{2U_0}{m} (1 - e^{-kx})}}$$

①

Skiptum um breytu

$$u = e^{-kx} \rightarrow du = -k e^{-kx} dx = -k u dx$$

$$\rightarrow dx = \frac{du}{-ku} e^{kx_0}$$

$$\tau = \int_0^{x_0} \frac{dx}{\sqrt{\frac{2U_0}{m} (1 - e^{-kx})}} = -\frac{1}{k} \sqrt{\frac{m}{2U_0}} \int_1^{e^{kx_0}} \frac{du}{u \sqrt{1-u}}$$

Þetta heildi má finna á fylgiblöðum prófsins (E10.c)

$$\tau = \frac{1}{k} \sqrt{\frac{m}{2U_0}} \left[\ln \left\{ \frac{2}{u} \sqrt{1-u} + \frac{2}{u} - 1 \right\} \right]_1^{e^{kx_0}} = \frac{1}{k} \sqrt{\frac{m}{2U_0}} \left[\ln \left\{ 2e^{kx_0} \sqrt{1 - e^{-kx_0}} + 2e^{kx_0} - 1 \right\} - \ln \left\{ 2 \sqrt{1-1} + 2 - 1 \right\} \right]$$

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Svarið er því

$$\tau = \frac{1}{k} \sqrt{\frac{m}{2U_0}} \left\{ \ln \left[2e^{kx_0} \sqrt{1 - e^{-kx_0}} + 1 \right] - 1 \right\}$$

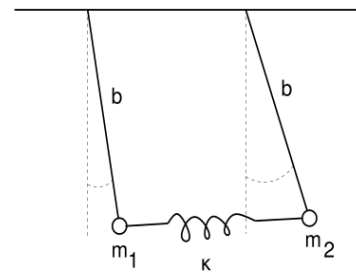
Ágætt er að kanna að $\lim_{x_0 \rightarrow 0} \tau(x_0) = 0$

eins og á að vera, og afellulausnin fyrir stórt kx_0 er, $kx_0 \gg 1$

$$\tau \xrightarrow{kx_0 \gg 1} \frac{4kx_0}{k} \sqrt{\frac{m}{2U_0}} = 4x_0 \sqrt{\frac{m}{2U_0}}$$

③

Dæmi 2



a) Án nálgunar

$$T = \frac{m_1}{2} (b \dot{\theta}_1)^2 + \frac{m_2}{2} (b \dot{\theta}_2)^2$$

$$U = m_1 g b (1 - \cos \theta_1) + m_2 g (1 - \cos \theta_2) + \frac{k}{2} \left[b \sin \theta_1 - b \sin \theta_2 \right]^2$$

b) Gerum nálgun fyrir smá horn

$$\sin \theta \approx \theta, \cos \theta \approx 1 - \frac{\theta^2}{2}$$

$$U = \frac{g b}{2} \left[m_1 \theta_1^2 + m_2 \theta_2^2 \right] - \frac{k b^2}{2} (\theta_1 - \theta_2)^2$$

og hreyfiorkan er óbreytt

④

c) því verða

$$M = \begin{pmatrix} m_1 b^2 & 0 \\ 0 & m_2 b^2 \end{pmatrix}, \quad A = \begin{pmatrix} m_1 g b + k b^2 & -k b^2 \\ -k b^2 & m_2 g b + k b^2 \end{pmatrix}$$

Eigingildisverkefnið er

$$A \bar{a} = \omega^2 M \bar{a} \quad \text{margföldun með } M^{-1} \text{ eyðileggur samhverfuna}$$

því er einfaldast að krefjast að krefjast

$$\det \{ A - \omega^2 M \} = 0$$

$$\text{sem verður} \quad \begin{vmatrix} m_1 g b + k b^2 - \omega^2 m_1 b^2 & -k b^2 \\ -k b^2 & m_2 g b + k b^2 - \omega^2 m_2 b^2 \end{vmatrix} = 0$$

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Ákveðan verður því

$$m_1 m_2 b^2 \left[(g + \alpha_1 - \omega^2 b)(g + \alpha_2 - \omega^2 b) \right] - k^2 b^4 = 0 \quad \alpha_1 = \frac{k b}{m_1}$$

$$\alpha_2 = \frac{k b}{m_2}$$

$$\rightarrow g^2 + \alpha_1 \alpha_2 + \omega^4 b^2 - 2g\omega^2 b + g(\alpha_1 + \alpha_2) - \omega^2(\alpha_1 + \alpha_2)b - \frac{(k b)^2}{m_1 m_2} = 0$$

$$b^2 \omega^4 - \omega^2 \{ 2g + \alpha_1 + \alpha_2 \} b + (g + \alpha_1)(g + \alpha_2) - \frac{(k b)^2}{m_1 m_2} = 0$$

svo lausnin er

$$\omega_{\pm}^2 = \frac{g}{b} + \frac{1}{2b}(\alpha_1 + \alpha_2) \pm \frac{1}{2b} \sqrt{(2g + \alpha_1 + \alpha_2)^2 b^2 - 4 \left[(g + \alpha_1)(g + \alpha_2) - \frac{(k b)^2}{m_1 m_2} \right]}$$

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d) skoðum lausnina fyrir tvennir þegar $m_1 = m_2$

$$\omega_{\pm}^2 = \frac{g}{b} + \frac{k}{m} \pm \frac{1}{2b} \sqrt{4b^2 \left(g + \frac{k b}{m} \right)^2 - 4b^2 \left[\left(g + \frac{k b}{m} \right)^2 - \frac{(k b)^2}{m^2} \right]}$$

$$= \frac{g}{b} + \frac{k}{m} \pm \frac{1}{b^2} \sqrt{\frac{(k b)^2}{m^2}} = \frac{g}{b} + \frac{k}{m} \pm \frac{k}{m}$$

$$\rightarrow \omega_{\pm}^2 = \begin{cases} \frac{g}{b} + \frac{2k}{m} \\ \frac{g}{b} \end{cases}$$

sem er þekkt lausn fyrir tvo eins pendúla

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Daemi 3 Stjarnfluttur, $I_3 > I_2 = I_1$

Klukkan $t=0$

$$\bar{\omega} = \omega_1 \hat{e}_1 + \lambda \hat{e}_2 + \mu \hat{e}_3, \quad \lambda, \mu \ll \omega_1$$

skoðum tímapróun snúningsins með trúflanareikningi, jöfnur Eulers eru

$$\left. \begin{aligned} (I_2 - I_3) \lambda \dot{\mu} - I_1 \dot{\omega}_1 &= 0 \\ (I_3 - I_1) \mu \dot{\omega}_1 - I_2 \dot{\lambda} &= 0 \\ (I_1 - I_2) \lambda \dot{\omega}_1 - I_3 \dot{\mu} &= 0 \end{aligned} \right\}$$

$$\dot{\lambda} = \left(\frac{I_3 - I_1}{I_3} \omega_1 \right) \mu$$

$$\dot{\mu} = \left(\frac{I_1 - I_2}{I_3} \omega_1 \right) \lambda \rightarrow \dot{\mu} = 0 \rightarrow \mu = \text{fasti}$$

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Því fæst

$$\dot{\lambda} = \underbrace{\left(\frac{I_3 - I_1}{I_2} \omega_1 \right)}_{\text{fasti}} \mu = \text{fasti}$$

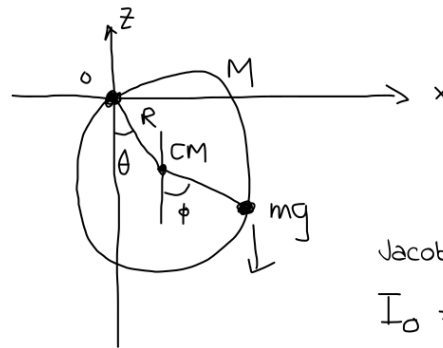
$$\rightarrow \lambda(t) = At + B, \quad \text{þar sem A og B eru fastar}$$

Samkvæmt þessu truflanamati vex því λ (eða ω_2) líulega og hættir að vera smátt miðað við ω_1 , þetta er truflanalausn og sýnir að snúningurinn er í upphafi óstöðugur. Vissulega mun ω_1 minnka og orkan haldast föst þegar nákvæmari lausn er skoðuð.

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Daemi 4 gjöra og frjáls perla a)

Hnitin eru



$$x = R \{ \sin \theta + \sin \phi \}$$

$$y = R \{ \cos \theta + \cos \phi \}$$

Jacob Steiner:

$$I_0 = I_{CM} + MR^2 = 2MR^2$$

$$U = U_{arc} + U_m = \left\{ -MgR \cos \theta \right\} + \left\{ -mgR \cos \theta - mgR \cos \phi \right\}$$

$$= -MgR \cos \theta - mgR \{ \cos \theta + \cos \phi \}$$

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$$T = \underbrace{\frac{I_0 \dot{\theta}^2}{2}}_{\text{gjörð}} + \underbrace{\frac{m}{2} \{ \dot{x}^2 + \dot{y}^2 \}}_{\text{perla}} \quad \left. \begin{array}{l} \dot{x} = R \{ \dot{\theta} \cos \theta + \dot{\phi} \cos \phi \} \\ \dot{y} = R \{ \dot{\theta} \sin \theta + \dot{\phi} \sin \phi \} \end{array} \right\} \quad (11)$$

$$T = MR^2 \dot{\theta}^2 + \frac{mR^2}{2} \left\{ (\dot{\theta} \cos \theta + \dot{\phi} \cos \phi)^2 + (\dot{\theta} \sin \theta + \dot{\phi} \sin \phi)^2 \right\}$$

$$\approx MR^2 \dot{\theta}^2 + \frac{mR^2}{2} \left\{ \dot{\theta}^2 + 2\dot{\theta}\dot{\phi} + \dot{\phi}^2 \right\}$$

$$U \approx \frac{MgR}{2} \theta^2 + \frac{mgR}{2} \{ \theta^2 + \phi^2 \} \quad \text{í lægstu nálgun fyrir hornin}$$

b) Tvö alhnit, ϕ og θ

$$L \approx MR^2 \dot{\theta}^2 + \frac{mR^2}{2} \{ \dot{\theta}^2 + 2\dot{\theta}\dot{\phi} + \dot{\phi}^2 \} - \frac{MgR}{2} \theta^2 - \frac{mgR}{2} \{ \theta^2 + \phi^2 \}$$

Hreyfijöfnurnar eru því

$$\frac{\partial L}{\partial \theta} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = 0$$

$$-MgR\theta - mgR\theta - \frac{d}{dt} \left\{ 2MR^2 \dot{\theta} + mR^2 \dot{\theta} + mR^2 \dot{\phi} \right\} = 0$$

$$-mgR\phi - \frac{d}{dt} \left\{ mR^2 \dot{\theta} + mR^2 \dot{\phi} \right\} = 0$$

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bær má því skrifa sem

$$(2M+m)\ddot{\theta} + m\ddot{\phi} + \frac{g(M+m)}{R}\theta = 0$$

$$\ddot{\theta} + \ddot{\phi} + \frac{g}{R}\phi = 0$$

c) Afskráðungar

$$P_{\theta} = \frac{\partial L}{\partial \dot{\theta}} = 2M\dot{\theta} + mR^2\{\dot{\theta} + \dot{\phi}\}$$

$$P_{\phi} = \frac{\partial L}{\partial \dot{\phi}} = mR^2\{\dot{\phi} + \dot{\theta}\}$$

Kórjöfnur Hamiltons

$$\left. \begin{aligned} \dot{q} &= \frac{\partial H}{\partial p} \\ -\dot{p} &= \frac{\partial H}{\partial q} \end{aligned} \right\}$$

$$\dot{\theta} = \frac{\partial H}{\partial P_{\theta}} = \frac{2(P_{\theta} - P_{\phi})}{mR^2}$$

$$-\dot{P}_{\theta} = \frac{\partial H}{\partial \theta} = 2R\theta(m+M)$$

$$\dot{\phi} = \frac{\partial H}{\partial P_{\phi}} = \frac{2}{mR^2}(P_{\phi} - P_{\theta}) + \frac{P_{\phi}}{mR^2}$$

$$-\dot{P}_{\phi} = \frac{\partial H}{\partial \phi} = gmR\phi$$

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d) Fall Hamiltons

$$H = P_{\theta}\dot{\theta} + P_{\phi}\dot{\phi} - L$$

$$= 2M(R\dot{\theta})^2 + m(R\dot{\theta})^2 + mR^2\dot{\theta}\dot{\phi} + mR^2\dot{\phi}^2 + mR^2\dot{\theta}\dot{\phi} - M(R\dot{\theta})^2 - \frac{mR^2}{2}\{\dot{\theta}^2 + 2\dot{\theta}\dot{\phi} + \dot{\phi}^2\} + \frac{MgR}{2}\theta^2 + \frac{mgR}{2}\{\theta^2 + \phi^2\}$$

$$= M(R\dot{\theta})^2 + \frac{mR^2}{2}\{\dot{\theta}^2 + 2\dot{\theta}\dot{\phi} + \dot{\phi}^2\} + \frac{MgR}{2}\theta^2 + \frac{mgR}{2}\{\theta^2 + \phi^2\}$$

$$= \frac{(P_{\theta} - P_{\phi})^2}{mR^2} + \frac{P_{\phi}^2}{2mR^2} + \frac{gR}{2}\{(M+m)\theta^2 + m\phi^2\}$$

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Daemi 5 Miðlaegt mætti (ekki háð horni) $U(r) = U_0 \ln(r/r_0)$

U_0 og r_0 jákvæðir fastar

a) Virkamættið

$$V(r) = U(r) + \frac{l^2}{2mr^2}, \quad l = mr^2\dot{\theta} \quad \text{fasti, þar sem hornið kemur ekki í falli Lagrange}$$

b) Póhnit

$$L = T - U = \frac{mr\dot{r}^2}{2} + \frac{m(r\dot{\theta})^2}{2} - U_0 \ln(r/r_0)$$

c) Hnitð θ er rásað þar sem það kemur ekki fyrir í $L(r, \dot{r}, \dot{\theta})$

d) Finna geisla stöðugar hringbrautar. Byrjum á hreyfijöfnunni f)

$$\frac{\partial L}{\partial r} - \frac{d}{dt}\left(\frac{\partial L}{\partial \dot{r}}\right) = 0 \rightarrow \ddot{r} - \frac{l^2}{m^2 r^3} + \frac{U_0}{mr} = 0$$

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Jafnvægisfjarlægð

$$\frac{\partial V}{\partial r} = \frac{U_0}{r} - \frac{l^2}{m r_0^3} = 0 \rightarrow r_0^2 = \frac{l^2}{U_0 m}$$

$$\rightarrow r_0 = \sqrt{\frac{|l|}{U_0 m}}$$

e) Greinilega eru ekki til efri mörk fyrir hverfipunga agnarinnar

g) smáar sveiflur, nágun hreyfijöfnu

$$\ddot{r} - \frac{l^2}{m^2 r^3} + \frac{U_0}{m r} = 0, \quad r = r_0 + \delta, \quad \frac{1}{(r_0 + \delta)^3} \approx \frac{1}{r_0^3} \left[1 - \frac{3\delta}{r_0} \right]$$

$$\rightarrow \ddot{\delta} - \frac{l^2}{m^2 r_0^3} \left[1 - \frac{3\delta}{r_0} \right] + \frac{U_0}{m r_0} \left[1 - \frac{\delta}{r_0} \right] \approx 0$$

Lágmarksskilyrðin

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Því stendur eftir hreyfijafnan fyrir smáar sveiflur

$$\ddot{\delta} + \left[\frac{3l^2}{m^2 r_0^4} - \frac{U_0}{m r_0^2} \right] \delta = 0$$

$$\rightarrow \frac{3l^2 U_0^2 m^2}{m^2 l^4} - \frac{U_0^2 m}{m l^2} = 3 \frac{U_0^2}{l^2} - \frac{U_0^2}{l^2} = \frac{2U_0^2}{l^2}$$

$$\rightarrow \omega = \sqrt{2} \left| \frac{U_0}{l} \right|$$

h) $U(r)$ er rétta þyngdarmætti punktuppsprettu í tvívídd. Ögn um hana er alltaf bundin, hver sem orka hennar eða skriðþungi er. Þetta er á allt annan hátt í þrívídd eins og við höfum skoðað.

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